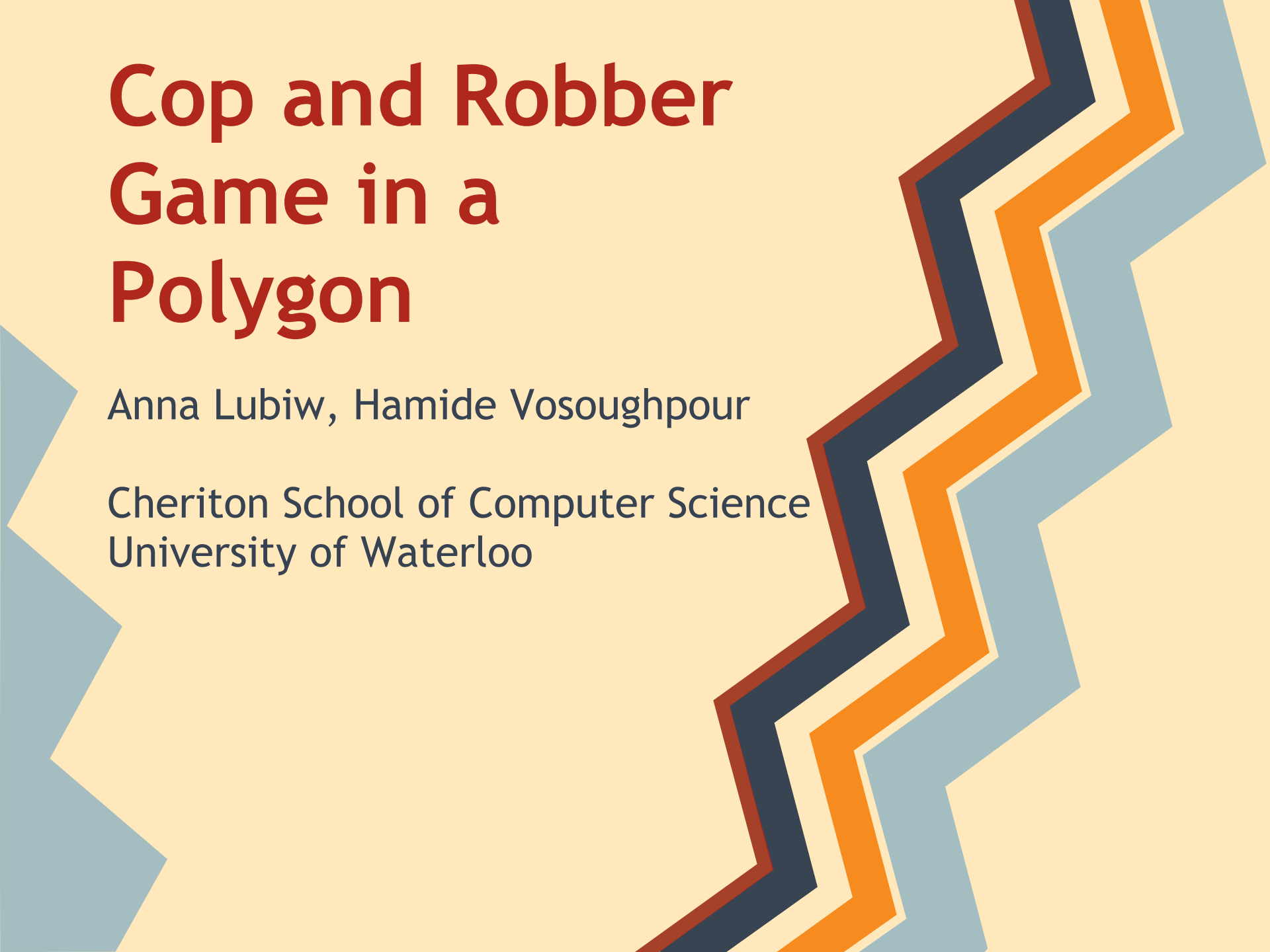


Cop and Robber Game in a Polygon

Anna Lubiw, Hamide Vosoughpour

Cheriton School of Computer Science
University of Waterloo

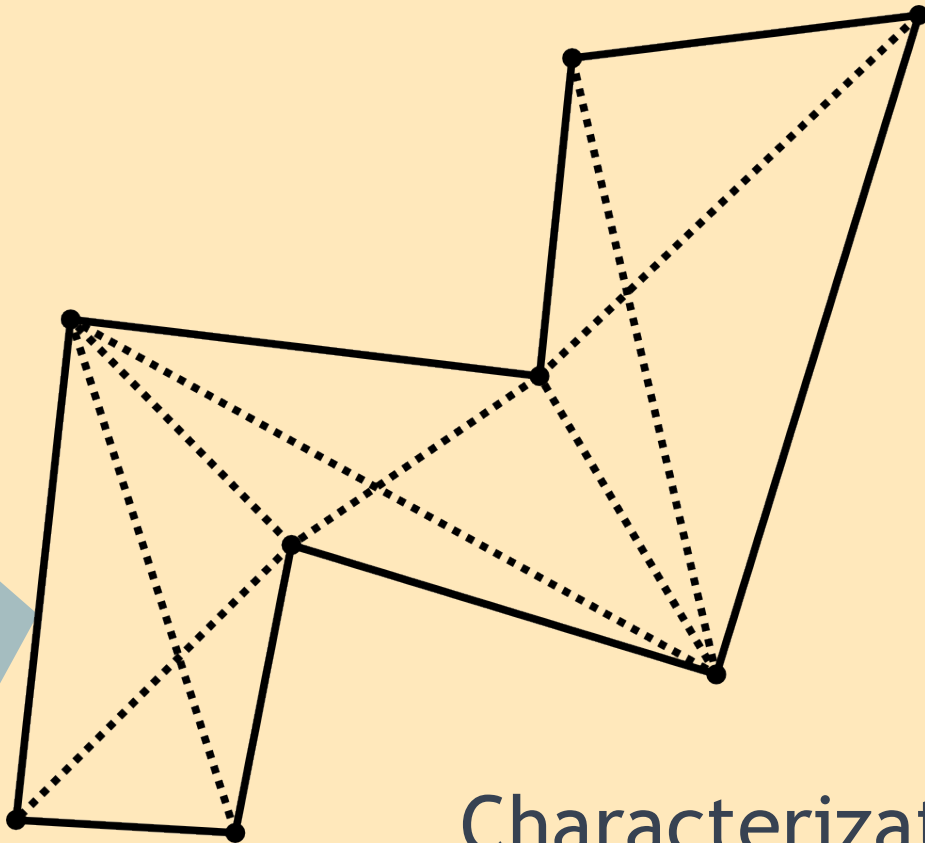


Cop and Robber Game in Polygons

Visibility Graphs

Dismantlable
Graphs

Visibility Graph

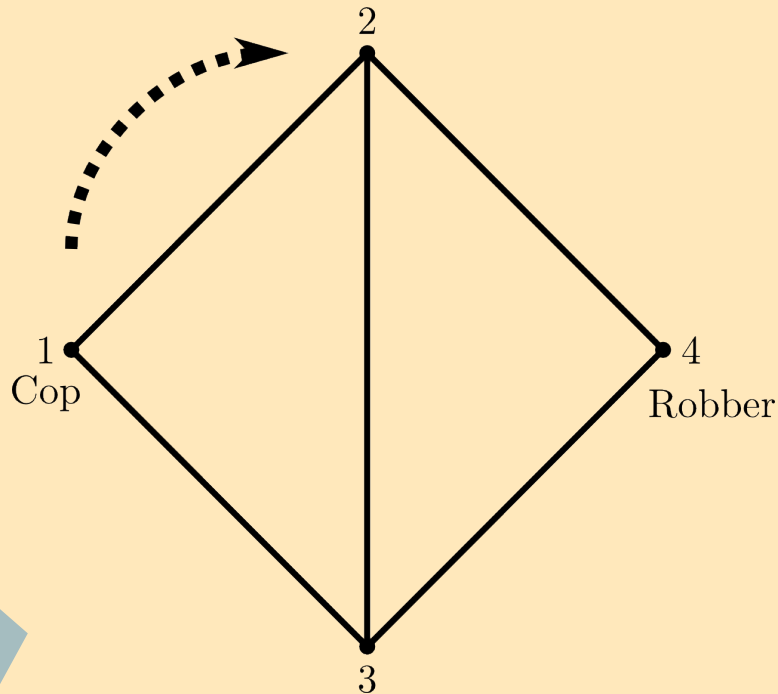


V = vertices

$E = (u, v): u \text{ sees } v$

Characterization and recognition is still an open problem.

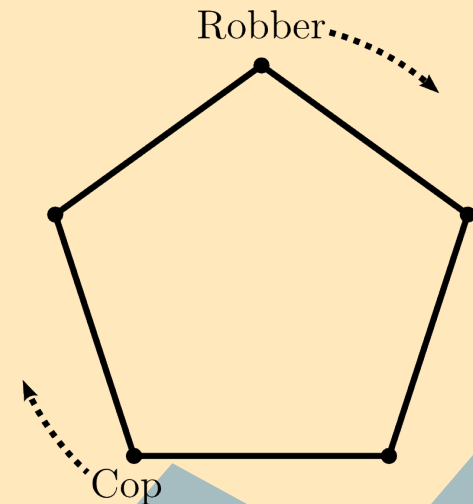
Cop and Robber Game



- cop & robber on vertices
- take turns, move on edges

Vertex 2 dominates vertex 4:

$$N[4] \subseteq N[2]$$

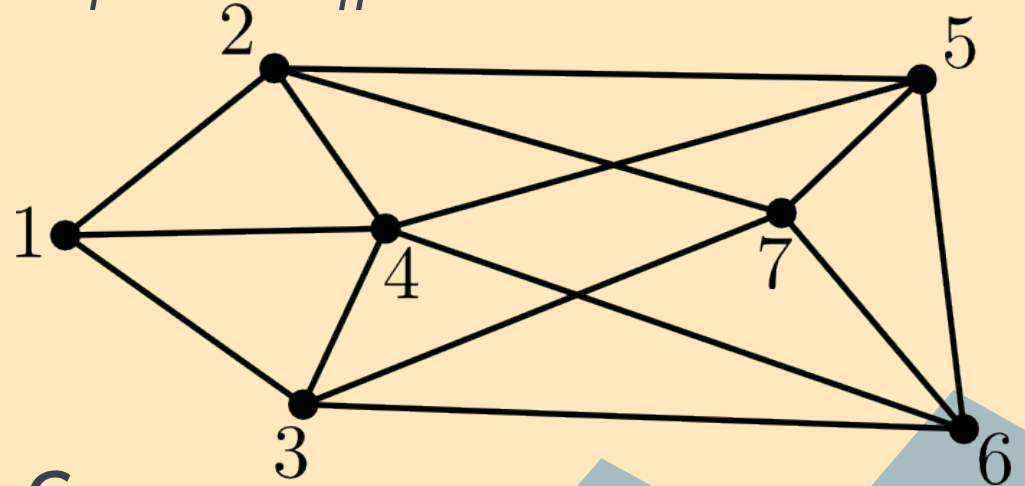


Dismantlable Ordering

Vertex ordering of $G=(V,E)$

$$v_1 v_2 \cdots v_n$$

s.t. v_i dominated by some v_j , $j>i$ in G_i (the subgraph of vertices v_i, \dots, v_n)



1 dominated by 4

2 dominated by 5 in G_2

Dismantlability and Cop-win

Theorem by Nowakowski and Winkler 1982:

A graph $G=(V,E)$ is cop-win iff dismantlable.

- recognition in polynomial time
- cop optimal strategy in polynomial time
- number of turns bounded by n

2-Dismantlability

The graph has at least 2 dominated vertices u_1 and u_2 and $G-u_1-u_2$ is 2-dismantlable recursively.

- number of turns bounded by $n/2$

Visibility Graphs

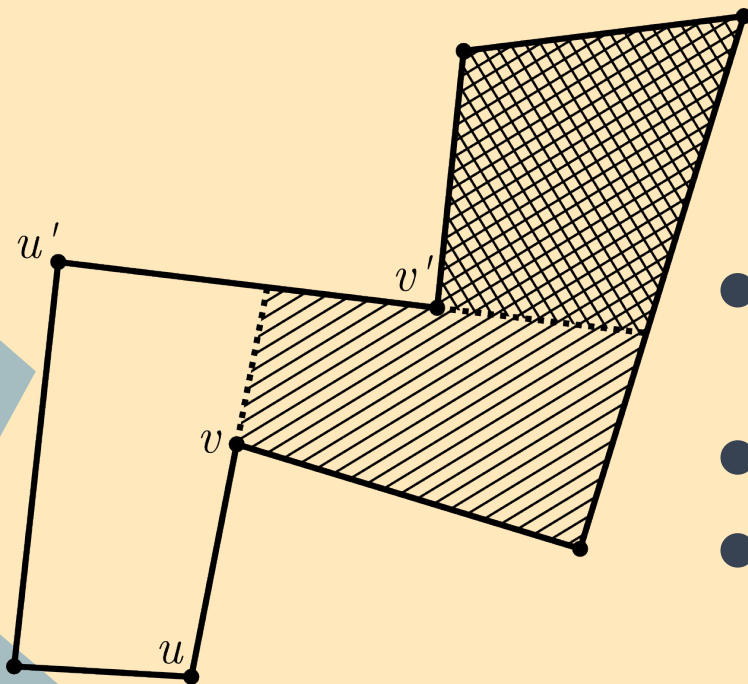
Dismantlable Graphs



Visibility Graphs are Dismantlable

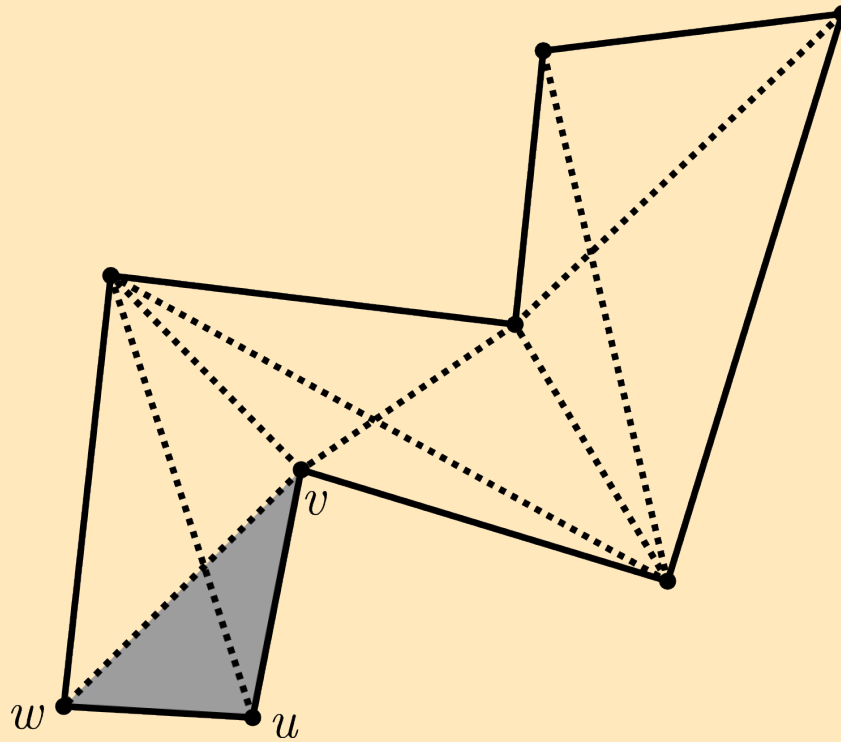
Proved by Aichholzer et al. 2011

Idea: A maximal pocket gives a dominated vertex



- pocket(u, v) maximal by containment.
- pocket(u', v') not maximal
- pocket(u, v) maximal $\Rightarrow u$ is dominated by v .

Visibility Graphs are Dismantlable

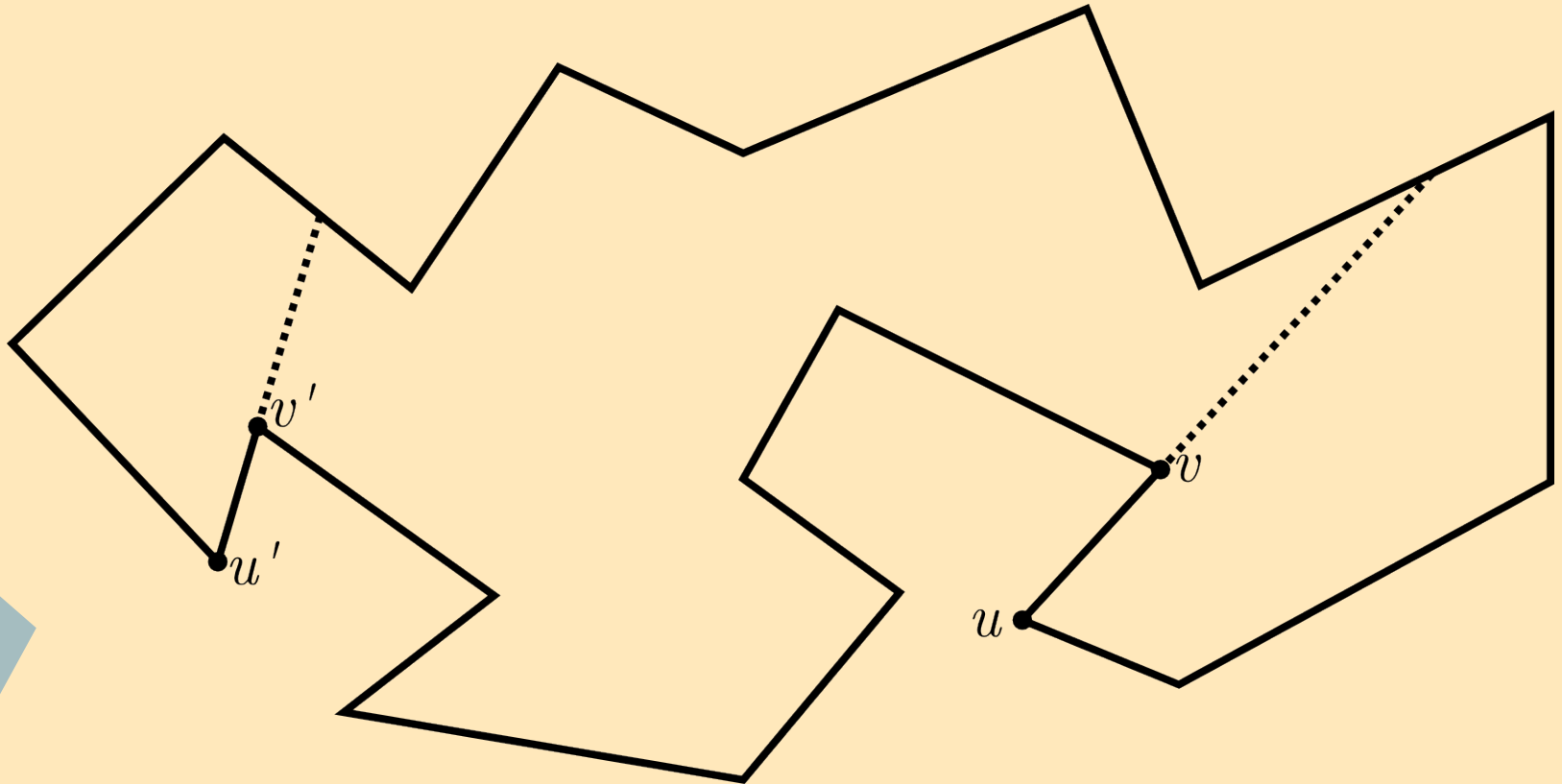


Remove u from visibility graph ~ Remove $\triangle uvw$ from polygon

Cops and Robbers on Visibility Graph

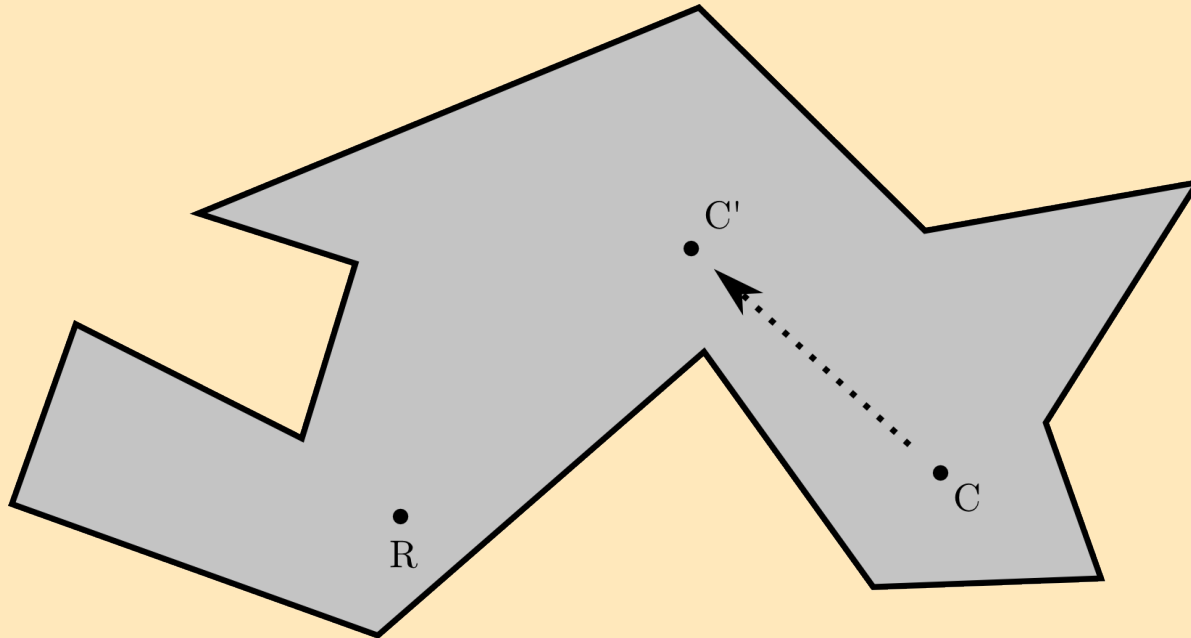
- always cop-win
- the cop may only use reflex vertices to win
- the game finishes after r turns (number of reflex vertices)

Visibility Graphs are 2-Dismantlable



u dominated by v
 u' dominated by v'

Cops and Robbers in Polygons



- Take turns
- Move on straight line inside the polygon
- Have full information about each other's location
- Cop's goal is to capture the robber, i.e. move to robber's position.

Background on Pursuit Evasion

- Continuous vs discrete space (limited speed)
- Continuous vs discrete moves (man and lion problem)
- Capture vs see the evader.
- Group of pursuers vs a single pursuer.
- Full information vs partial/no information about the evader's position.

Our Result

Infinite Visibility Graph

- Vertex for every point inside polygon.
- Edge (p,q) if p sees q .

We Prove

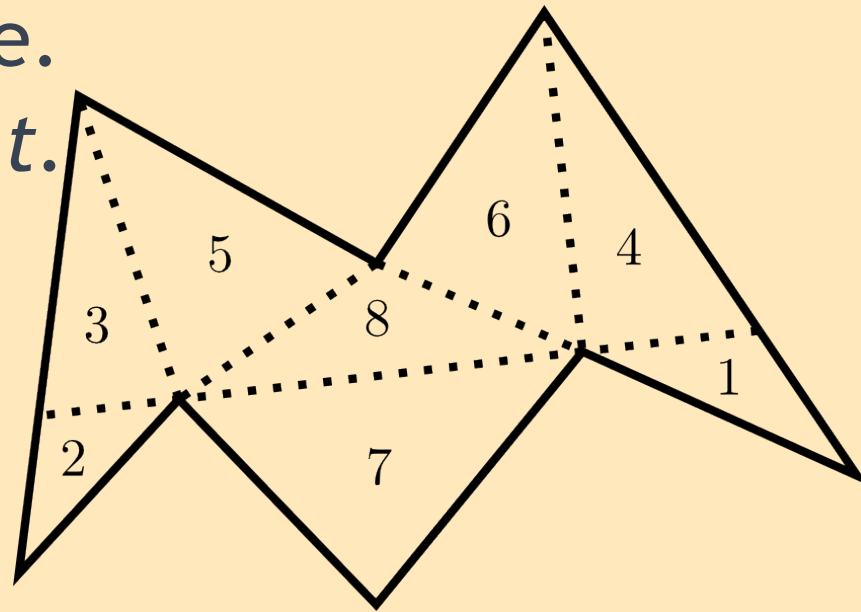
- The game is cop-win
- Using 2-dismantlable ordering of triangles in polygons.

Proof Idea

Successively remove dominated triangles.

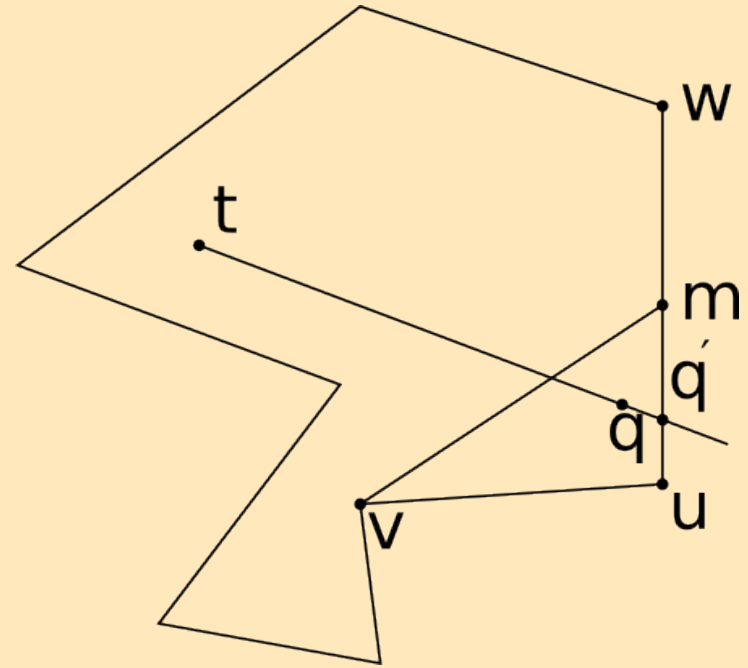
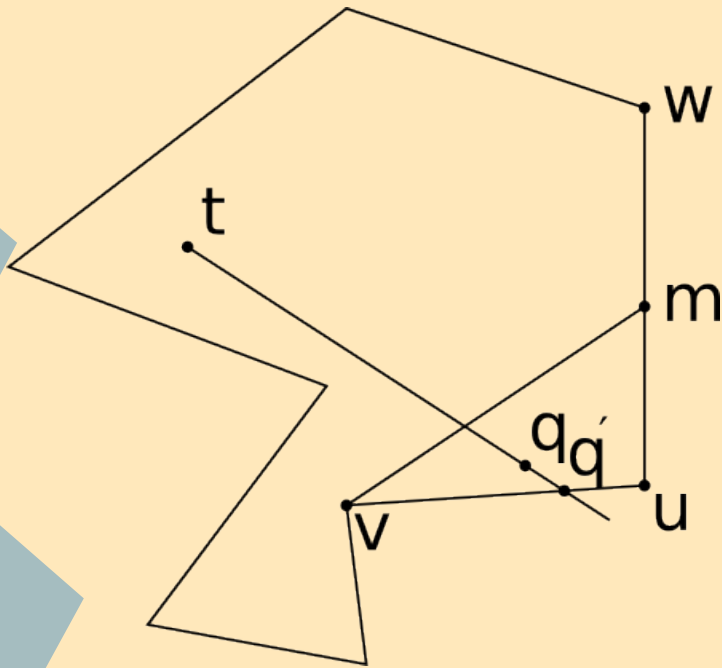
R dominated by v if all points $p \in R$ are dominated by v i.e.

p sees $t \Rightarrow v$ sees t .



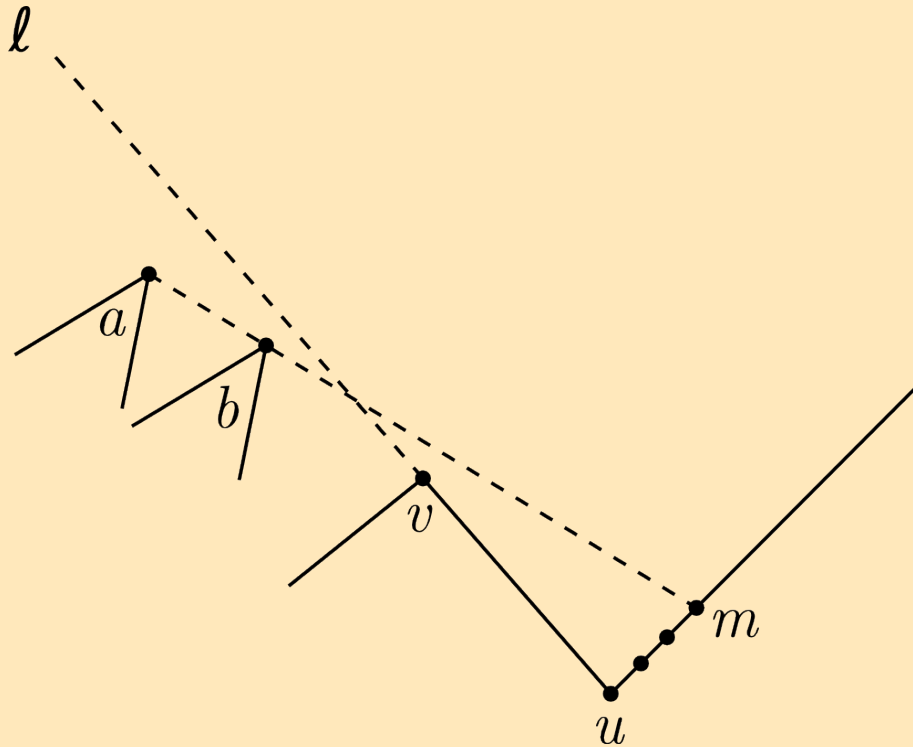
triangles' vertices are not necessarily polygon vertices.

Dominated Triangle



If boundary of $\triangle vum$ is dominated by v , all points q inside the triangle are also dominated.

How to choose point m ?

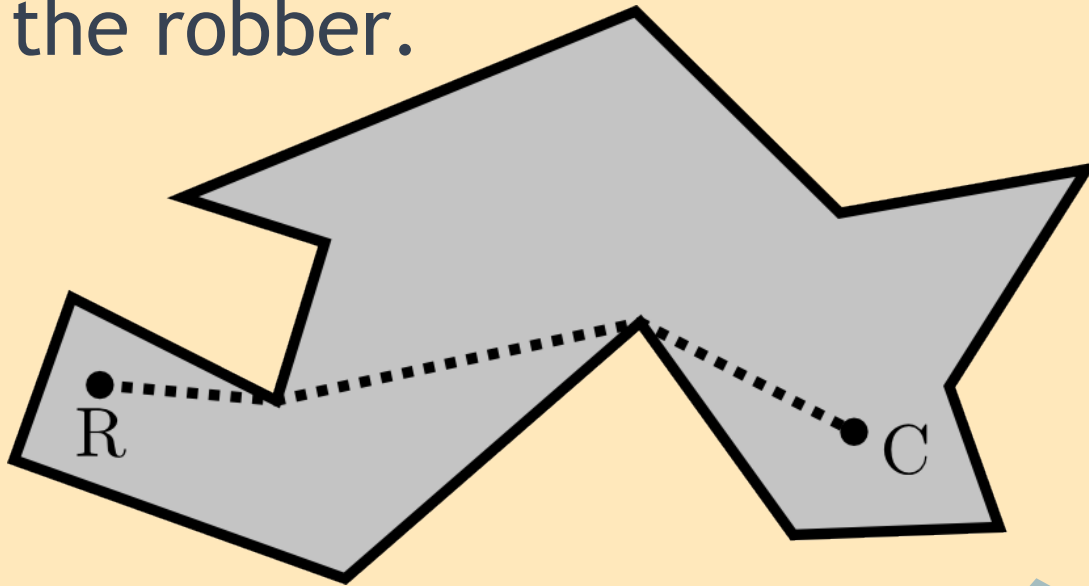


- $\text{Pocket}(u, v)$ is maximal
- m is reflex collinear
- get $O(n^2)$ triangles.

Simple Strategy

We also showed a simple cop move rule to win:

The cop goes to the first step on the *shortest path* to the robber.

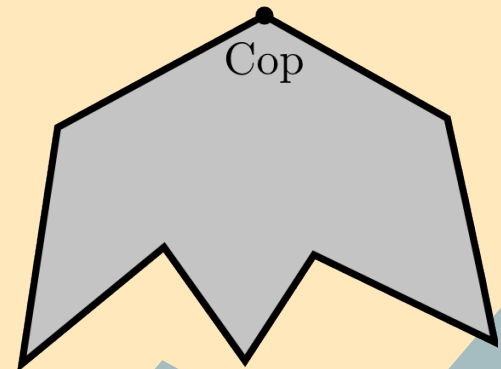
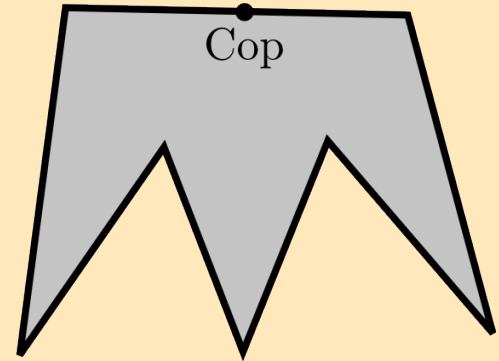


Conclusions

- Provide one answer to Hahn's question (2002) of finding non-trivial classes of infinite cop-win graphs
- One step into visibility graph characterization.
- The more natural way to model pursuit evasion problem than limited speed for real polygonal environments.

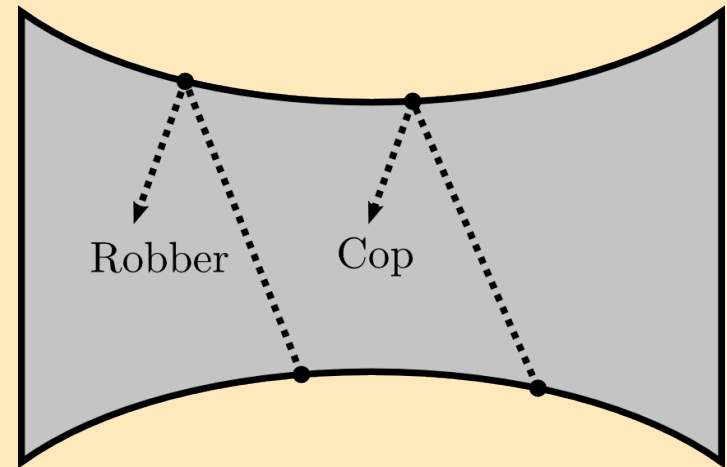
Open Questions

- How hard is to find the optimal cop strategy
 - polynomial when the cop is limited to vertices (maybe boundary)



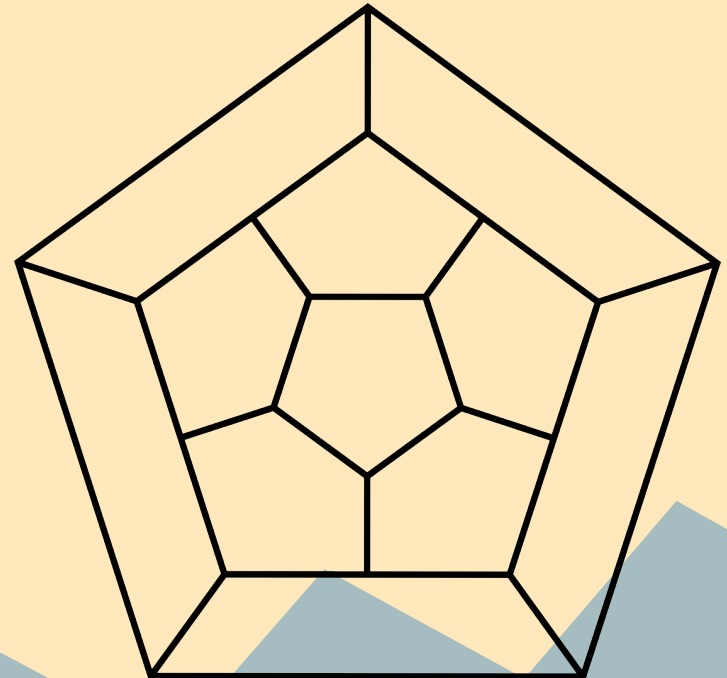
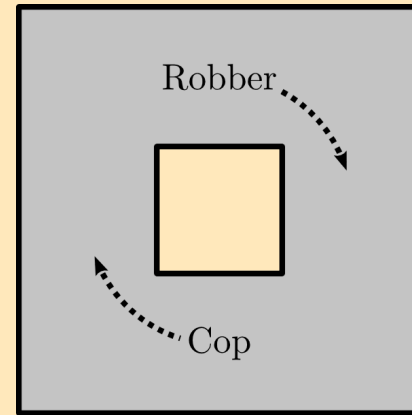
Open Questions

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- Game in curvy environments
 - no winning strategy for cop moving on boundary



Open Questions

- How hard is to find the optimal cop strategy
 - polynomial when the cop is limited to vertices (maybe boundary)
- Game in curvy environments
 - no winning strategy for cop moving on boundary
- Number of sufficient cops in polygons with holes
 - 3 cops are needed in some situations (based on the planar graph by Aigner and Fromme (1984) that needs 3 cops)





THANK YOU